

Lecture 8 - Monte Carlo Sampling

Reminder: goal of stat mech
to calculate average properties

$$\langle O \rangle = \int d\vec{x} O(\vec{x}) P(\vec{x})$$

$$\vec{x} = \{x_1 \dots x_{3N}, p_1 \dots p_{3N}\} \text{ or}$$
$$= \{x_1 \dots x_{3N}\} \text{ if } O \text{ doesn't}$$

depend on \vec{p} and

$$P(\vec{x}, \vec{p}) = P(\vec{x}) P(\vec{p})$$

eg, @ const NVT , usually

$$H(\vec{x}, \vec{p}) = \sum_{i=1}^{3N} p_i^2 / 2m_i + U(\vec{x})$$

$$P(\vec{x}) = \int d\vec{p} P(\vec{x}, \vec{p}) = \frac{e^{-\beta U(\vec{x})}}{\int dx e^{-\beta U(x)}}$$

But, even if know $u(x)$,
cannot compute $\langle \cdot \rangle$ directly
for most problems, high dimension

Idea: produce representative
set of configurations $\{\vec{x}_t\}$
s.t. x_t distributed according to
target distribution

More specifically, have correct
relative weights. So eg for

Boltzmann distribution

$$\begin{aligned} P(\vec{x}_j) / P(\vec{x}_i) &= \frac{e^{-\beta u(\vec{x}_j)}}{e^{-\beta u(\vec{x}_i)}} = e^{-\beta [u(\vec{x}_j) - u(\vec{x}_i)]} \\ &= e^{-\beta \Delta u_{ij}} \end{aligned}$$

How can we do this? ① Going to generate a "Markov Chain"

This means a set of CFGs

$$\vec{x}_1 \rightarrow \vec{x}_2 \rightarrow \vec{x}_3 \rightarrow \dots \rightarrow \vec{x}_T$$

made by some rule where

$P(\vec{x}_t \rightarrow \vec{x}_{t+1})$ only depends on what \vec{x}_t is (not $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_{t-2}$)

② It can be proven that if our rule satisfies "detailed balance" then sampling will converge

"detailed balance" - each microscopic step follows equilibrium rule

$$P(x_t) P(x_t \rightarrow x_{t+1}) = P(x_{t+1}) P(x_{t+1} \rightarrow x_t)$$

We do this by choosing
the rule $P(\vec{x}_t \rightarrow \vec{x}_{t+1})$

This is actually made of two
parts!

$$P(x_t \rightarrow x_{t+1}) = P_{\text{gen}}(x_t \rightarrow x_{t+1}) \cdot P_{\text{acc}}(x_t \rightarrow x_{t+1})$$

Plugging into D.B. (switch to x, y)

$$P(x) P_{\text{gen}}(x \rightarrow y) P_{\text{acc}}(x \rightarrow y) = P(y) P_{\text{gen}}(y \rightarrow x) P_{\text{acc}}(y \rightarrow x)$$

$$\Rightarrow P_{\text{acc}}(x \rightarrow y) = \frac{P(y) P_{\text{gen}}(y \rightarrow x)}{P(x) P_{\text{gen}}(x \rightarrow y)} \cdot P_{\text{acc}}(y \rightarrow x)$$

$\underbrace{\hspace{10em}}_{r(x \rightarrow y) \text{ "rate"}}$

How can we get this:

Metropolis Rule (1953)

$$P_{acc}(x \rightarrow y) = \min[1, r(x \rightarrow y)]$$

Why does this work?

either $r(x \rightarrow y) > 1$ or $r(y \rightarrow x) > 1$ lets try both (a)

$$a: r(y \rightarrow x) = \frac{1}{r(x \rightarrow y)} < 1$$

$$\frac{P_{acc}(x \rightarrow y)}{P_{acc}(y \rightarrow x)} = \frac{1}{\left[\frac{1}{r(x \rightarrow y)} \right]} = r(x \rightarrow y)$$

$$b: r(y \rightarrow x) = 1$$

$$\frac{P_{acc}(x \rightarrow y)}{P_{acc}(y \rightarrow x)} = r(y \rightarrow x)$$

Algorithm: Start at x_t

① Propose x_{t+1} w/ prob $q_{\text{gen}}(x_t \rightarrow x_{t+1})$

gen random # $r \in [0, 1)$

if $r < q_{\text{acc}}(x_t \rightarrow x_{t+1})$:

② Move to x_{t+1}

if not:

duplicate x_t i.e. $x_{t+1} = x_t$

③ back to 1

Let's look at $r(x \rightarrow y)$

$$r(x \rightarrow y) = \frac{q_{\text{gen}}(y \rightarrow x)}{q_{\text{gen}}(x \rightarrow y)} \cdot \frac{P(y)}{P(x)}$$

Choose q_{gen} &

$P(x)$ is target distr

So far Metropolis

$$P(y)/P(x) = e^{-\beta \Delta U_{xy}}$$

What about this P_{gen}

Usually choose P_{gen} to be

Symmetric st $\frac{P_{gen}(x \rightarrow y)}{P_{gen}(y \rightarrow x)}$ cancel

Eg: Suppose we want to sample
1 particle in HO $U(x) = \frac{1}{2} kx^2$



Rule could be

$$X_{t+1} = X_t + \xi \tau_2$$

$\tau_2 \in (-1, 1)$ uniform random

ξ is max step size

Reverse move equally likely

In this case Metropolis rule simplifies to $P_{acc} = \min[1, e^{-\beta\Delta U}]$

Accept always if energy goes down

Accept sometimes if energy goes up

Time move rule to get accept prob $\sim 0.25-0.5$

trade off between efficiency and exploration, eg size of ϵ

bigger move, more likely to increase ϵ more

Reminder: even if initial cty not good, will eventually sample from target P (if ergodic)

Do we have to use metropolis?

There are other rules:

Eg: Glauber rule

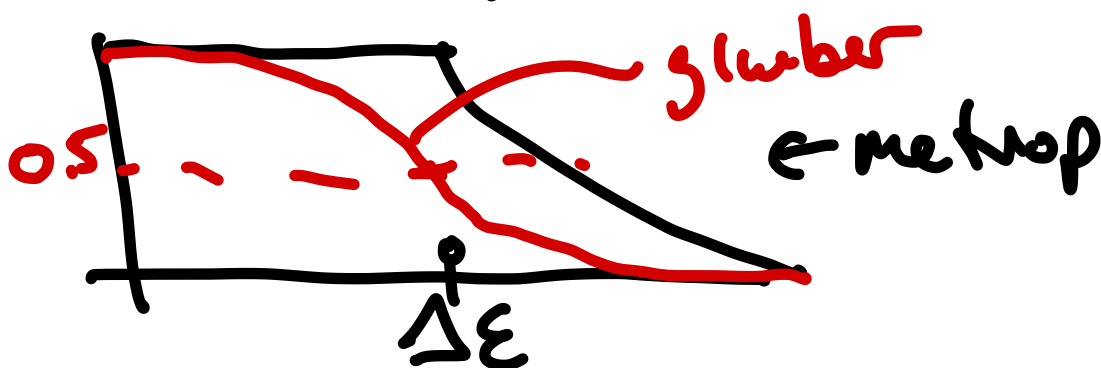
$$P_{acc}(x \rightarrow y) = \frac{1}{2} [1 - \tanh(\beta \Delta E_{xy})]$$
$$= \frac{e^{-\beta \Delta E_{xy}/2}}{e^{\beta \Delta E_{xy}/2} + e^{-\beta \Delta E_{xy}/2}}$$

why?

$$\Delta E_{xy} = E_y - E_x$$

$$\Delta E_{yx} = E_x - E_y = -\Delta E_{xy}$$

So $\frac{P_{acc}(x \rightarrow y)}{P_{acc}(y \rightarrow x)} = e^{-\beta \Delta E_{xy}}$ ✓



Why MC & why not?

① Easy

② can choose smart MC
moves which sample space
much faster

Why not?

① Not real dynamics (if you care)
Only static properties right (usually)

② Usually only small moves accepted
Eg in liquid, move 1 MC not
all at once as in MD