

Lecture 2 - Microcanonical Ensemble

Last time

Microstate:

$$\vec{X} = \{x_1, \dots, x_{3N}, p_1, \dots, p_{3N}\}$$

$A(\vec{x})$ measurable quantity

Observable quantity

$$\langle A \rangle = \int d\vec{X} P(\vec{X}) A(\vec{X})$$

$P(x)$ depends only on the
Macro state

Eg const N, V, T [canonical ensemble]

$$P(x) = \frac{1}{Z} e^{-\beta \mathcal{H}(x)}$$

\mathcal{H} ← total energy

$$\beta \leftarrow \frac{1}{k_B T} \quad \text{high } T - \text{small } \beta$$

harmonic oscillator - 1d

$$\mathcal{H}(x, p) = \frac{1}{2} kx^2 + p^2/2m$$

$$Z = \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dp e^{-\beta \mathcal{H}(x, p)}$$

$$Z = 2\pi \frac{k_B T}{\omega}$$

$$\omega = \sqrt{k/m}$$

$$\langle E \rangle = \frac{1}{Z} \int d\vec{x} \mathcal{H}(\vec{x}) e^{-\beta \mathcal{H}(\vec{x})}$$

$$\langle \epsilon \rangle = -\frac{\partial \log Z}{\partial \beta} = \frac{-1}{Z} \frac{\partial Z}{\partial \beta}$$

$$= + \frac{1}{Z} \int dx \mathcal{H}(x) e^{-\beta \mathcal{H}(x)}$$

no M,
K

$$Z_{SHC} = 2\pi \frac{k_B T}{\omega} = 2\pi \cdot \frac{1}{\beta \omega}$$

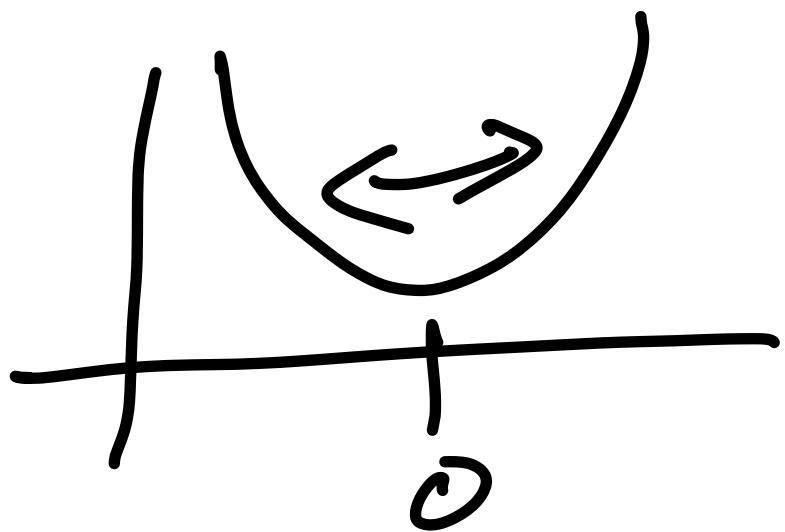
$$-\frac{\partial \log Z}{\partial \beta} = -\frac{\partial (-\log \beta)}{\partial \beta} = \frac{1}{\beta} = k_B T$$

$$\log Z = \log \left(\frac{2\pi}{\beta \omega} \right) = \log \left(\frac{2\pi}{\omega} \right) - \log \beta$$

$$\langle A \rangle = \frac{1}{Z} \int d\vec{x} A(\vec{x}) e^{-\beta H(x)} = \int dx A(x) P(x)$$

$$\langle x \rangle = \frac{1}{Z} \int_{-\infty}^{\infty} x \left[\int_{-\infty}^{\infty} p \right] e^{-\beta \left[\frac{1}{2} kx^2 + \frac{p^2}{2m} \right]}$$

$$u = x^2 \quad du = 2x dx$$



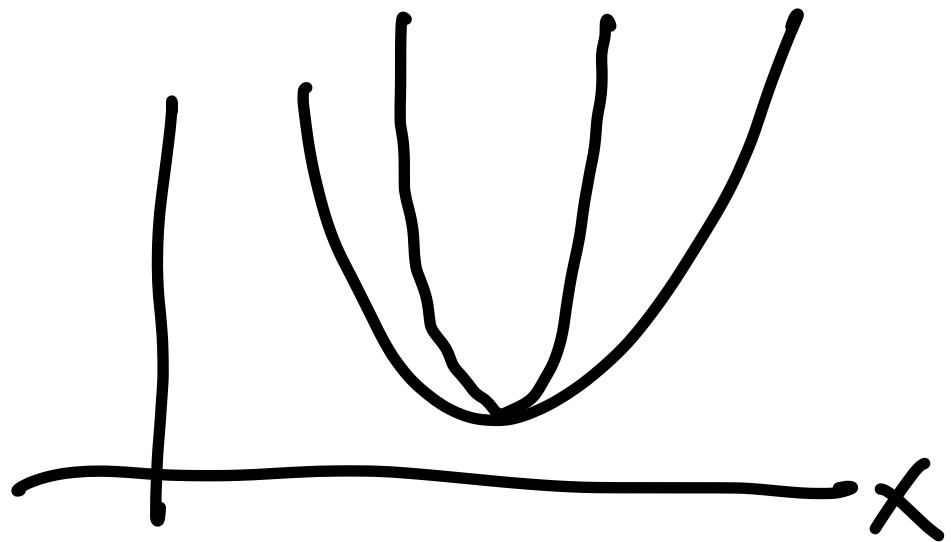
$$\begin{aligned} \langle u \rangle &= \int dx \int dp \frac{1}{2} kx^2 e^{-\alpha x^2} \\ &\int dx x^2 e^{-\alpha x^2} \end{aligned}$$

$$\langle \varepsilon \rangle = -\frac{\partial \log Z}{\partial \beta}$$

$$H = -\frac{e^2}{4\pi\epsilon r}$$

← can't
solve
directly

$$\langle \varepsilon \rangle = k_B T$$



$$Z = 2\pi \frac{k_B T}{\varepsilon}$$

↑

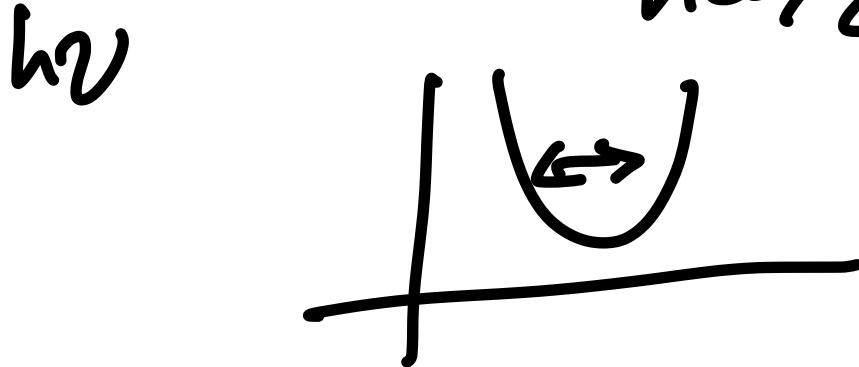
$Z \sim \text{number of stacks}$

\vec{x} particular state of system
classical mechanics - continuous
quantum mechanics - discrete

$$H = p^2/2m + \frac{1}{2}kx^2 \leftarrow \begin{matrix} \text{s. h. o.} \\ \text{quantum} \end{matrix}$$

$$E_n = \hbar\omega(n + \frac{1}{2})$$

$\hbar\omega/2 \leftarrow$ zero point energy

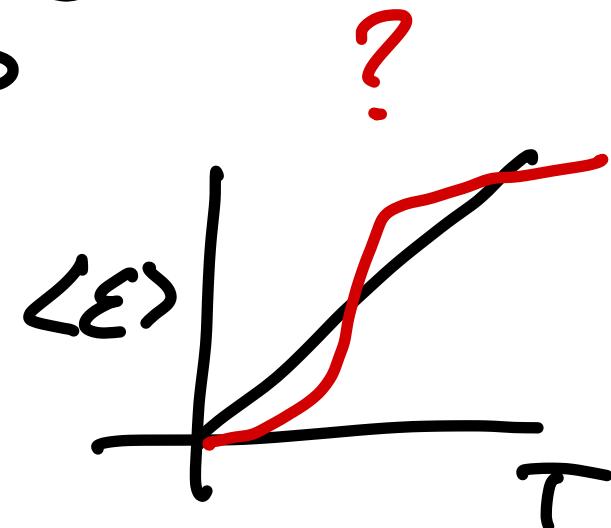


$$P(\text{state}) = \frac{1}{Z} e^{-\beta H(\text{state})}$$

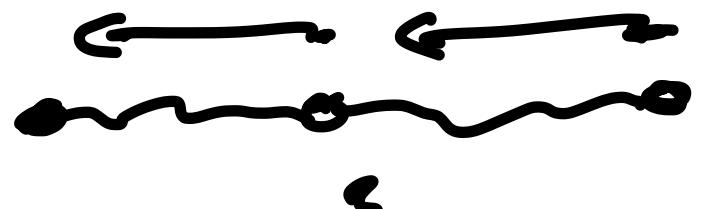
$$n = 0, \dots, \infty$$

$$Z = \sum_{n=0}^{\infty} e^{-\beta E_n} = \sum_{n=0}^{\infty} e^{-\beta n\omega(n+\frac{1}{2})}$$

$$\langle E \rangle = \frac{1}{Z} \sum_{n=0}^{\infty} E_n e^{-\beta E_n}$$



$H(\omega)$: Solve Z exactly
 $\langle E \rangle$ by $-\partial \log Z / \partial \beta$



sum over springs

$$H = \sum_{i=1}^N \frac{p_i^2}{2m_i} + \sum_{i=1}^N \frac{1}{2} k_i (l_i - l_0)^2$$

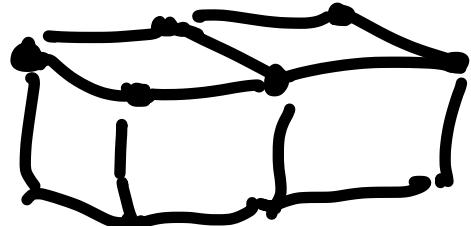
first rest

N H.O. in dimensions
any dimensions

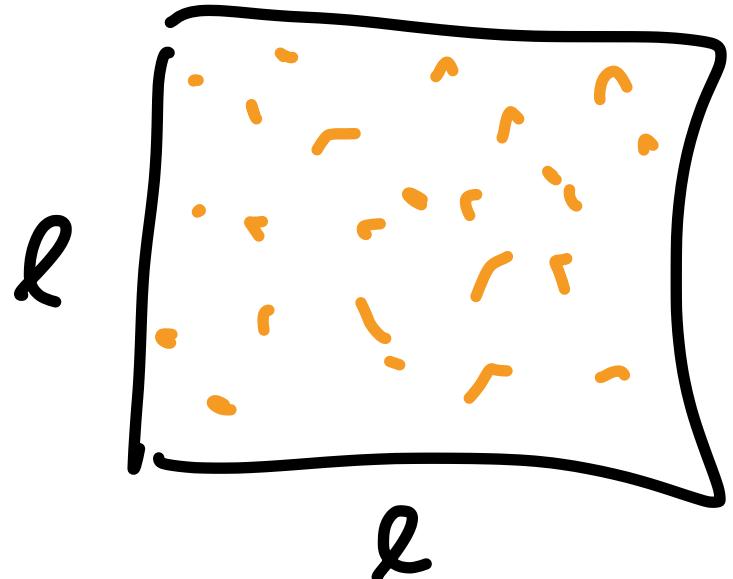
$$\sum_{i=1}^N \sum_{j=i+1}^N \frac{1}{2} k_{ij} (r_{ij} - r_{ij}^0)^2$$

$$\mathcal{E} = \frac{1}{2} \sum_{i=1}^N k_i \tilde{u}_i^2$$

\tilde{u}_i ~ normal mode



Return to system of N particles
in a box



N in box volume $V = l^d$

assert:

box is closed no
exchange of M 's

is isolated
no exchange of E
(heat)

N particles follow Newton's
equations of motion

Classical mechanics:

$$F_i = \underline{m_i \ddot{x}_i} \quad \vec{F} = m \vec{a}$$

$$X_0 = \{ \overset{x,y,z...}{x_1, \dots, x_{3N}}, \underset{\sim}{\{p_x, p_y, p_z\}} \}_{i=1}^{3N} \text{ initial state}$$

know X from $t \in (-\infty, \infty)$

$$= \{ \overset{\rightarrow}{r_1}, \dots, \overset{\rightarrow}{r_N}, \overset{\rightarrow}{p_1}, \dots, \overset{\rightarrow}{p_N} \}_{i=1}^N \quad (x, y, z), \quad (p_x, p_y, p_z)_N$$

$$a_i = \frac{dv_i}{dt} = \frac{1}{m} \frac{dp_i}{dt} \leftarrow$$

$$F = -\nabla U(\vec{x}_1, \dots, \vec{x}_N) \leftarrow$$

↗ $\nabla = (\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \dots, \frac{\partial}{\partial x_N})$

$$F_i = m_i a_i = m_i \frac{dU_i}{dt} = m_i \frac{d^2 x_i}{dt^2}$$

$$v = \frac{dx}{dt}$$

$$\int_0^T dt v = \int_0^T dt \frac{dx}{dt}$$

integrate: $x(T) - x(0) = v T$

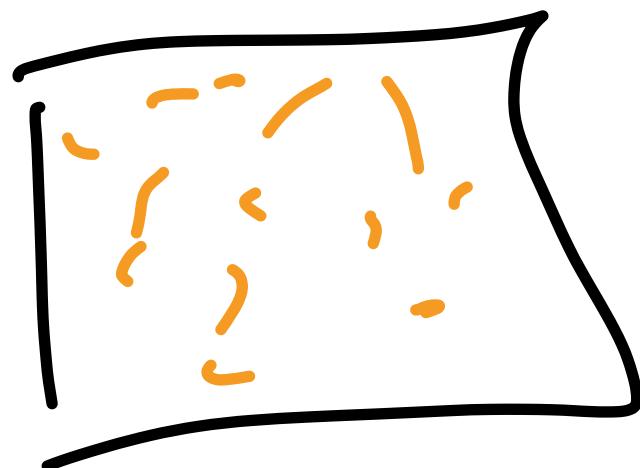
" $d = vt$ " $\begin{cases} d = vt \\ + \frac{1}{2}at^2 \end{cases}$

$$a = \frac{dv}{dt} \Rightarrow v(T) - v(0) = a T$$

$$U = -\frac{G m_1}{r}$$

$$F = \frac{G m_1}{r^2}$$

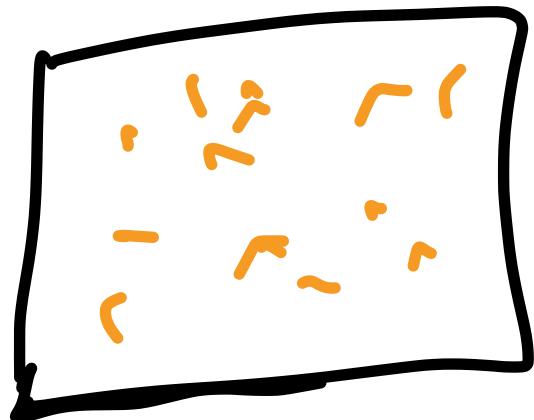
$$F = -\frac{\partial U}{\partial r} = \frac{G m_1 m_2}{|r_1 - r_2|^2}$$



$$N \sim N_A$$

No external forces!

Newton's equations conserve E_{total}



State:

N, V, E

Microcanonical ensemble

How many microstates are there

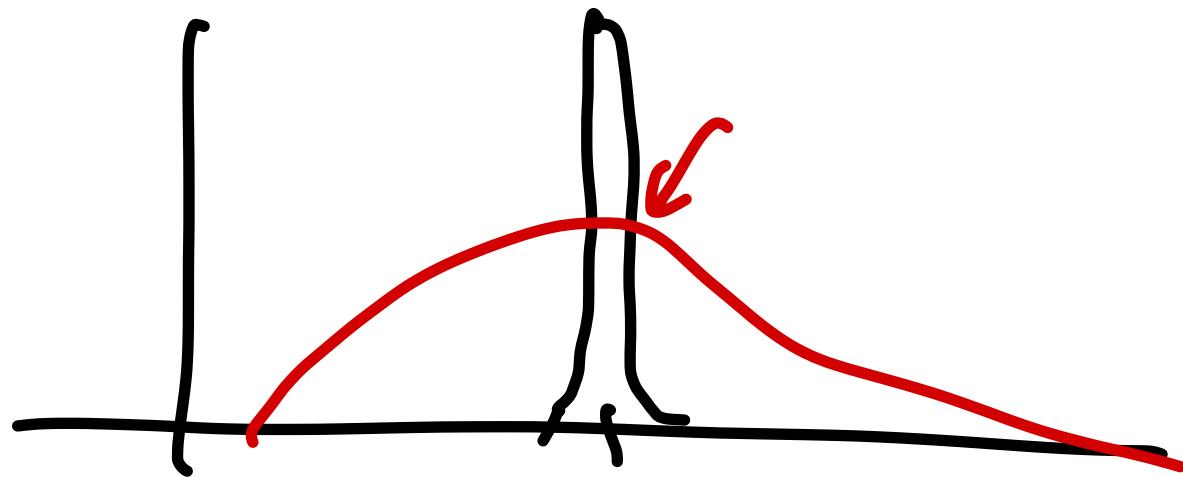
$$Z = \int d\vec{x} \delta(H(x) - E)$$

← can confine particle in box

↑

number
of states

$$S(x) \sim \begin{cases} 1 & \text{when } x=0 \\ 0 & \text{when } x \neq 0 \end{cases}$$

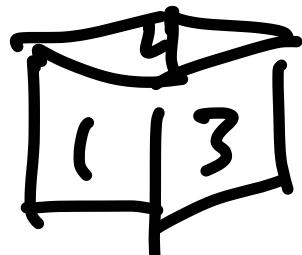


$$\int_{-\infty}^{\infty} dx \delta(x) = 1$$

$$\int_{-\infty}^{\infty} dx f(x) \delta(x-a) = f(a)$$

$$P(\vec{x}) = \begin{cases} \frac{1}{z} & \text{if } H(x) = \epsilon \\ 0 & \text{if not} \end{cases}$$

$$\int P(x) d\vec{x} = ($$

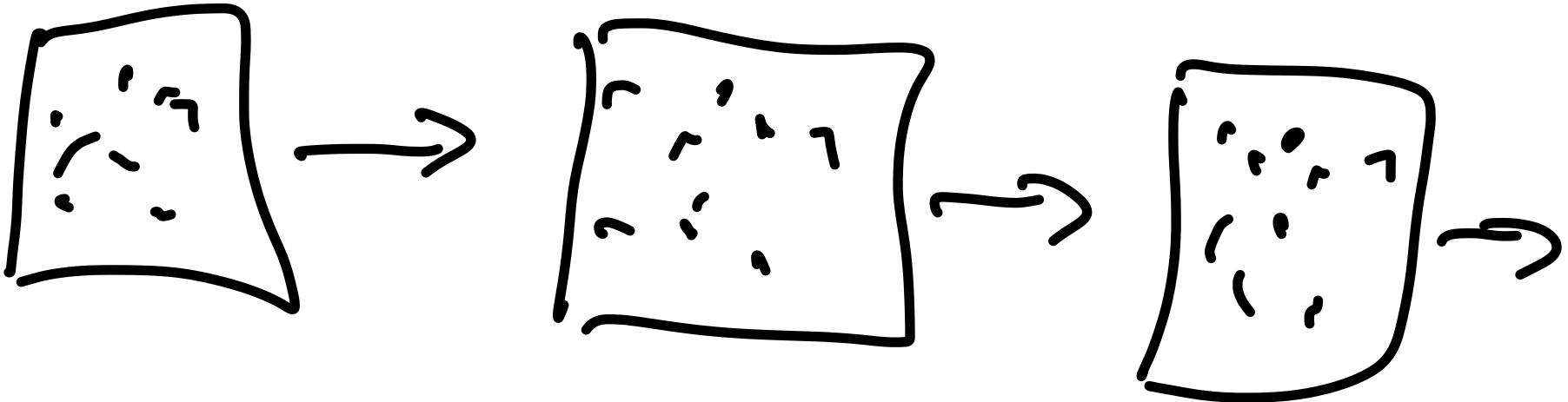


x weighted dice

$$P(1, \dots, 6) = \frac{1}{6}$$

$$P(1) = 5/6$$

$$P(2 \dots 6) = \frac{1}{30}$$



w/ Newton's equations ↑

trajectory

$$X(t) \sim X(t=0), x(t=r), x(t=v)$$
$$\downarrow \quad \downarrow \quad \downarrow$$
$$\epsilon \quad \epsilon \quad \epsilon$$

$\langle kE \rangle$ by thermometer

αT

$$\langle kE \rangle_{\text{time}} = \frac{1}{N_t} \sum_{i=1}^{N_t} kE(t)$$

if system can access all allowed states

assume
 $t \rightarrow \infty$

$$\langle A \rangle_{\text{ensemble}} = \langle A \rangle_{\text{time}}$$