

# Canonical Ensemble

Discuss HW  
Survey

## Other thermodynamic ensembles

Idea: Our hypothesis before was that if we could enumerate all the states of a system and the likelihood of seeing them, then we could predict any observable:

$$\langle A \rangle = \sum_{\text{states}} P(n) A(n)$$

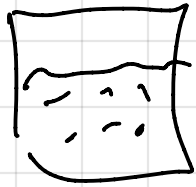
For closed isolated system, const  $N, V, E$   
we expect all states to have the same weight,  $\Omega(N, V, E)$  states

$$\langle A \rangle = \int d\vec{q} d\vec{p} \delta(H(\vec{q}, \vec{p}) - E) A(\vec{q}, \vec{p}) / \int d\vec{q} d\vec{p} \delta(H(\vec{q}, \vec{p}) - E)$$

But we don't live in an isolated closed system  $\rightarrow$

Chemistry usually happens at const

$T \& V$

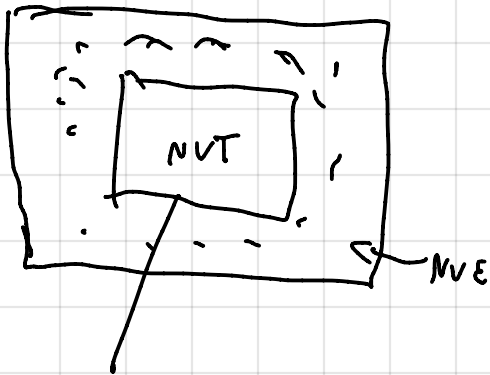


or  $T \& P$



So we have to see how likely a configuration is under these conditions

First, how is this dealt with in classical thermo



Impervious to particles, rigid, can exchange heat



can exchange heat, change volume (can show pressure equilibrate @ eq)

(can also have permeable membrane, eg  $\mu, V, T$ )

In microcanonical ensemble we had  $S(N, U, E)$  &

$$dS = \frac{1}{T} dE + \frac{P}{T} dV - \frac{\mu}{T} dN$$

lets rewrite in terms of  $E$ , b/c that may be easier to think about

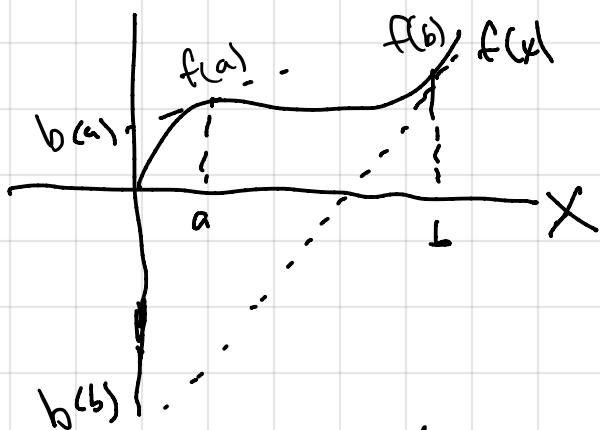
$$dE = TdS - PdV + \mu dN$$

This means  $T = \left(\frac{\partial E}{\partial S}\right)_{N,P}$   $P = -\left(\frac{\partial E}{\partial V}\right)_{S,N}$   $\mu = \left(\frac{\partial E}{\partial N}\right)_{S,V}$

And  $E(N, V, S)$  is a state function.

$T$ ,  $-P$ , and  $\mu$  are called conjugate variables of  $S$ ,  $V$  &  $N$  respectively

If we want a thermodynamic state function that depends on a conjugate variable instead of a current variable we have a trick called a Legendre transform



$$c(x) = \frac{df(x)}{dx} = f'(x) \Rightarrow x(c) = (f')^{-1}(c)$$

$$f(x) = x \frac{df(x)}{dx} + b(x) = x c(x) + b(x)$$

$$b(x) = f(x) - x c(x)$$

define new func  $\tilde{b}(c) = f(x(c)) - x(c)c(x)$

all extensive

Eg. have  $E(N, V, S)$  of our system, but can't measure  $S$ ...

New func  $A(N, V, T) = E(N, V, S) - S \left(\frac{\partial E}{\partial S}\right)_{N, V} = E(N, V, S) - TS$

$\nearrow$   $b(T)$        $\uparrow$   $c$  above       $\nwarrow$   $x$  above

$A$  is the "Helmholtz free energy"

Chain rule for  $A(N, U, T)$  gives

$$dA = \left( \frac{\partial A}{\partial T} \right)_{N, U} dT + \left( \frac{\partial A}{\partial U} \right)_{T, N} dU + \left( \frac{\partial A}{\partial N} \right)_{U, T} dN$$

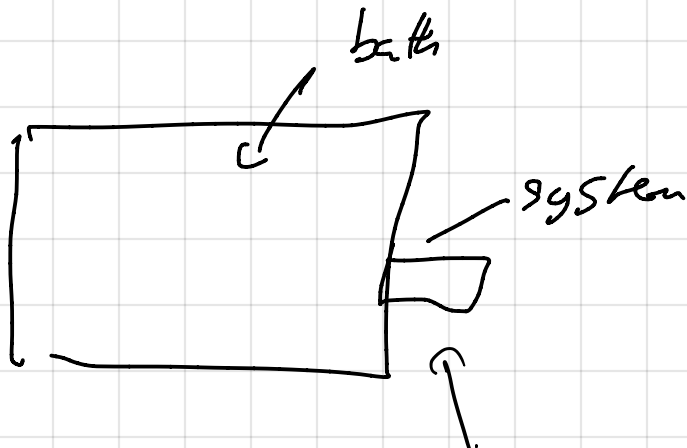
$$\begin{aligned} \text{but } A = E - TS \Rightarrow dA &= dE - Tds - SdT \\ &= (\underbrace{T ds - P dU + \mu dN}) - Tds - SdT \\ &= -SdT - PdU + \mu dN \end{aligned}$$

$$\Rightarrow \left( \frac{\partial A}{\partial T} \right)_{N, U} = -S \quad \left( \frac{\partial A}{\partial U} \right)_{N, T} = -P \quad \left( \frac{\partial A}{\partial N} \right)_{U, T} = \mu$$

\*

$A$  is like an energy

This is all classical thermo. To derive things based on a particle basis, we need to figure out how likely a state is, i.e. the inside of the partition function



$$H_{\text{total}} = H_{\text{sys}} + H_{\text{bath}}$$

$$\Rightarrow E_{\text{total}} = E_{\text{sys}} + E_{\text{bath}}$$

$$S_{\text{total}} = S_{\text{sys}} + S_{\text{bath}}$$

$$\vec{q}, \vec{p} = \vec{X}$$

Suppose the particles in the system have certain  $\vec{p}, \vec{q}$ , w/  $\epsilon_{\text{sys}} = \mathcal{H}_{\text{sys}}(\vec{p}, \vec{q})$ . The bath can be arranged many ways:

$$\Omega_b(N_b, V_b, E - \epsilon_{\text{sys}}) \propto f(\vec{q}, \vec{p})$$

$$E = E_{\text{sys}} + E_{\text{bath}} \quad \& \quad E_{\text{sys}} \text{ small} \Rightarrow E - E_{\text{bath}} \text{ is small}$$

Consider  $S_{\text{bath}}(N_{\text{bath}}, V_{\text{bath}}, E_{\text{bath}}) = S_{\text{bath}}(E_b)$

$$S_{\text{bath}}(E_b) \approx S_{\text{bath}}(E) + \left. \left( \frac{dS}{dE_b} \right) \right|_{E_b = E} (-\epsilon_{\text{sys}}) + \dots$$

$$\approx S_{\text{bath}}(E) - \frac{1}{T} \epsilon_{\text{sys}}$$

$$\text{Kloy } \Omega_b(N_b, V_b, E_b) \approx \text{const} \cdot e^{-\epsilon_{\text{sys}}/T}$$

$$f(\vec{q}, \vec{p}) \propto \Omega_b(N_b, V_b, E_b) = \text{const} \cdot e^{-\epsilon_{\text{sys}}/k_B T}$$

$$\propto e^{-\mathcal{H}_{\text{sys}}(\vec{x})/k_B T}$$

$$f(\vec{q}, \vec{p}) = e^{-\mathcal{H}_{\text{sys}}(\vec{x})/k_B T} / Z, \quad Z = \int d\vec{x} e^{-\beta \mathcal{H}_{\text{sys}}(x)}$$

and this is true even for systems where we're not thinking about particle systems, so

$$Z = \int d\vec{x} e^{-\beta H(x)} \quad \text{where } \beta = 1/k_B T$$

or for discrete systems  $Z = \sum_n e^{-\beta E_n}$

for  $N$  indistinguishable particles, often write

$$Q(N, V, T) = \frac{1}{h^{3N} N!} \int d\vec{p}^{3N} d\vec{q}^{3N} e^{-\beta H(\vec{q}, \vec{p})}$$

and  $f(\vec{p}, \vec{q}) = \frac{1}{h^{3N} N!} e^{-\beta H(\vec{p}, \vec{q})} / Q(N, V, T)$

$\xrightarrow{\text{cancels out}}$   
 $= e^{-\beta H(\vec{p}, \vec{q})} / Z(N, V, T) \quad \checkmark$

What is the connection between  $Q$  &  $\Omega(N, V, E)$ ?  
insert delta func

$$\begin{aligned}
 Q(N, V, T) &= \frac{1}{N! h^{3N}} \int d\vec{p}^{3N} d\vec{q}^{3N} \int_0^\infty dE \delta(H - E) e^{-\beta E} \\
 &= \int_0^\infty dE e^{-\beta E} \underbrace{\frac{1}{N! h^{3N}} \int d\vec{p}^{3N} d\vec{q}^{3N} \delta(H(\vec{p}, \vec{q}) - E)}_{\frac{1}{E_0} \Omega(N, V, E)}
 \end{aligned}$$

$$Q(N, U, T) = \frac{1}{\epsilon_0} \int_0^{\infty} dE e^{-\beta E} \Omega(N, U, E) \quad \leftarrow P(E)$$

so the canonical partition function is averaging the number of states at each energy if they have weight  $e^{-\beta E}$

Discrete,  $Q(N, U, T) = \sum_E \Omega(N, U, E) e^{-E/k_B T}$