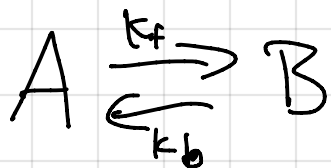


Non Equilibrium Pt 3

Other kinds of Brownian Motion

The general theory we are learning is useful for other kinds of random processes besides a particle in solution. To illustrate this, let's look at chemical reactions.

Simplest reaction is



expect $\frac{dA}{dt} = Bk_b - Ak_f$

$$\frac{dB}{dt} = Ak_f - Bk_b$$

In this case, we know

$$A + B = N \quad \leftarrow \text{const \# molecules}$$

@ Eq still true, $A_{eq} + B_{eq} = N$

In the spirit of our prev work, think about

$$A = A_{eq} + C, \quad A \text{ at a particular time is a deviation from eq}$$

This means $B = B_{eq} - C$

C measures reaction condition from all in

$$A \quad (C = B_{eq}) \text{ to all in } B \quad (C = -A_{eq})$$

Lastly, we have our detailed balance condition

$$A_{eq} k_f = k_b B_{eq}$$

Combining this info, we have

$$\frac{d(A_{eq} + C)}{dt} = -k_f(A_{eq} + C) + k_b(B_{eq} - C)$$

$$\frac{d(B_{eq} - C)}{dt} = k_f(A_{eq} + C) - k_b(B_{eq} - C)$$

$$\frac{dA_{eq}}{dt} = \frac{dB_{eq}}{dt} = 0$$

Subtract: $2 \frac{dC}{dt} = 2k_b(B_{eq} - C) - 2k_f(A_{eq} + C)$

$$\Rightarrow \frac{dC}{dt} = -(k_f + k_b)C$$

$$\Rightarrow C(t) = e^{-(k_f + k_b)t} \quad \leftarrow \tau_{rxn} = \frac{1}{k_f + k_b}$$

Macroscopic diff from eq decays to eq. exponentially

Ozuges Regression Hypothesis (1931)

Small fluctuations decay on the average

@ eq the same way as macroscopic ^{non eq} deviations

[not really a hypothesis, more like so for always true theory/law]

Makes sense, how would you know whether prepared in this state, or result of true dynamics

$$\Rightarrow \langle C(t)C(t') \rangle = \langle C^2 \rangle_{eq} e^{-(k_1 + k_2)(t-t')}$$

However, it can't be true that

the non eq condition goes to $C=0, \dots$

... and then the number of A & B are fixed, they have to fluctuate randomly

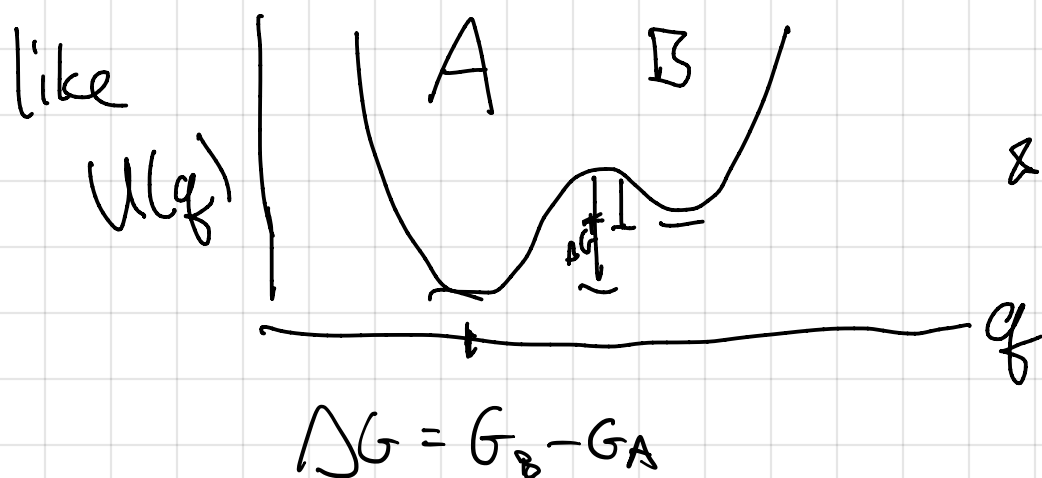
Have to maintain a $\langle C^2 \rangle_{eq}$ that is non-zero
 this is just like Brownian motion

so, postulate
$$\frac{dC}{dt} = -(k_1 + k_2)C + \delta F$$

$$\rightarrow \text{ \& now } \langle \delta F(t) \delta F(t') \rangle = 2(k_1 + k_2) \langle C^2 \rangle_{eq} \delta(t - t')$$

HW

This is a macroscopic view of chemical eq,
 but where do these rate constants come from. For this simple prob, we expect something



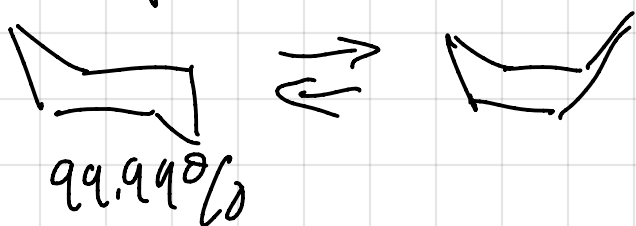
$$P_A / P_B \approx e^{-\beta \Delta G}$$

$$\& k_{A \rightarrow B} \propto e^{-\beta \Delta G_A^\ddagger}$$

$$k_{B \rightarrow A} \propto e^{-\beta \Delta G_B^\ddagger}$$

Now we have to connect this to the microscopic stat mech theory we've learned all semester. Molecularly, we still have $Q(x, p) = C \int d\vec{x} \int d\vec{p} e^{-\beta H(\vec{x}, \vec{p})}$

Real problem example could be



Define q by a collective coordinate
transition state @ q^\ddagger

Can define a function $H_A(q) = \begin{cases} 1, & q < q^\ddagger \\ 0, & q \geq q^\ddagger \end{cases}$ (can I in A)

$$\langle H_A \rangle = X_A = \frac{A_{eq}}{A_{eq} + B_{eq}}$$

Since H_A is 1 in A & 0 otherwise

$$\langle H_A^2 \rangle = \frac{H_A(A)^2 P(A) + H_A(B)^2 P(B)}{P(A) + P(B)} = \frac{P(A)}{P(A) + P(B)} = X_A$$

$$\Rightarrow \langle \delta H_A^2 \rangle = \langle H_A^2 \rangle - \langle H_A \rangle^2 = X_A - X_A^2 \\ = X_A(1 - X_A) = X_A X_B$$

Now, already said

$$\langle C(t) C(0) \rangle = e^{-t/\tau_{rxn}} \cdot \langle C^2 \rangle$$

similarly at a microscopic level

$$\langle \delta H_A(q(t)) \delta H_A(q(0)) \rangle = e^{-t/\tau_{rxn}} \langle \delta H_A^2 \rangle$$

$$\Rightarrow e^{-t/\tau_{rxn}} = \frac{\langle \delta H_A(q(t)) \delta H_A(q(0)) \rangle}{X_A X_B}$$

call $H_A(q(t)) = H_A(t)$ for simplicity

since we care how the number in A is changing in time
take time deriv

$$-\frac{1}{\tau_{rxn}} e^{-t/\tau_{rxn}} = \frac{\langle \dot{\delta H}_A(t) \delta H_A(0) \rangle}{X_A X_B}$$

Last time sort of discussed

↙ @ eq 50

HW?

$$\langle A(t) A(t') \rangle = \langle A(0) A(t' - t) \rangle = \langle A(t - t') A(0) \rangle \\ \Rightarrow \langle A(0) \dot{A}(t) \rangle = \langle \dot{A}(0) A(t) \rangle$$

For our case $-\langle \delta H_A(0) \delta H_A(t) \rangle = \langle \delta H_A(0) \delta H_A(t) \rangle$

Important to note $\frac{dH[q]}{dt} = \dot{q} \frac{d}{dq} H_A = -\dot{q} \delta(q - q^*)$

B changes from $0 \rightarrow -\infty \rightarrow 0$ instantaneously

$$\begin{aligned} \text{So } -\langle \delta H_A(0) \delta H_A(t) \rangle &= \langle -\dot{q}(0) \delta(q(0) - q^*) \delta H_A(q(t)) \rangle \\ &= \langle \dot{q}(0) \delta(q(0) - q^*) \delta H_B(q(t)) \rangle \end{aligned}$$

Since $H_B = 1 - H_A$

$$\text{and } \langle \dot{q}(0) \delta(q(0) - q^*) \rangle = 0$$

b/c velocity & configs are uncorrelated

Finally

$$\frac{1}{\tau_{rxn}} e^{-t/\tau_{rxn}} = \frac{1}{\lambda_A \lambda_B} \langle \dot{q}(0) \delta(q(0) - q^*) H_B(q(t)) \rangle$$

$\dot{q}(0) \delta(q(0) - q^*)$ on surface

Right side is flux crossing surface if ends up in B

Left side is simple exponential & cont account for really short time flux, here

evidence regression hypothesis is true only after coarse-graining over short time scales, so expect this to be true for $\tau_{\text{mol}} \ll t \ll \tau_{\text{rxn}}$ (fast barrier crossing)

$$\text{If so } \frac{1}{\tau_{\text{rxn}}} = k_f + k_b = \frac{1}{\chi_A \chi_B} \langle v(\omega) \delta(q - q^*) H_B(q(t)) \rangle$$

mult by χ_B & detailed balance

$$\chi_B(k_f + k_b) = \frac{B}{A+B} (k_f + k_b) = \frac{B/A}{1+B/A} (k_f + k_b) = \frac{\frac{k_f}{k_b}}{1 + \frac{k_f}{k_b}} (k_f + k_b) = k_f$$

$$\text{So } k_f = \frac{1}{\chi_A} \langle v(\omega) \delta(q - q^*) H_B[q(t)] \rangle$$

This connect microscopic behavior at the transition state to the macroscopic reaction rate

Fokker Planck Equation

General version of something like
Liouville eqn

Let $f(\vec{a}, t)$ be density like with phase
space before, but \vec{a} is n properties of
system rather than full phase space

$$\int d\vec{a} f(\vec{a}, t) = 1 \quad \text{required}$$

$$\text{let } \vec{v} = d\vec{a}/dt = \dot{\vec{a}}$$

$$\frac{\partial f(\vec{a}, t)}{\partial t} + \nabla_{\vec{a}} \cdot (\vec{v} f(\vec{a}, t)) = 0, \quad \text{change in density}$$

related to flux
of points

now suppose $\dot{\vec{a}} = \vec{v} + \vec{R}(t)$

$$\langle \vec{R}(t) \rangle = 0 \quad \& \quad \langle R_i(t) R_j(t') \rangle = 2B_{ij} \delta_{ij} \delta(t-t')$$

$$\frac{\partial f(\vec{a}, t)}{\partial t} + \nabla_{\vec{a}} \cdot (\dot{\vec{a}} f(\vec{a})) = \frac{\partial f}{\partial t} + \nabla_{\vec{a}} \cdot [(v(\vec{a}) + R(t)) f(\vec{a}, t)] = 0$$

$$L \equiv \nabla_a \cdot [\dot{a} \rightarrow] = \{ \quad , H \}$$

for no noise \nearrow det part

$$\frac{\partial f}{\partial t} + Lf = 0 \Rightarrow f(\vec{a}, t) = e^{-Lt} f(\vec{a}, 0)$$

$$\text{here } \frac{\partial f}{\partial t} = -Lf - \nabla_a \cdot \vec{R}(t) f(\vec{a}, t)$$

$$f(\vec{a}, t) = e^{-Lt} f(\vec{a}, 0) - \int_0^t ds e^{-(t-s)L} \nabla_a \cdot \vec{R}(s) f(\vec{a}, s)$$

$f(\vec{a}, t)$ only depends on noise up to time t

Sub back in & get

$$\frac{\partial f(\vec{a}, t)}{\partial t} + Lf(\vec{a}, t) = - \left[\nabla_a \cdot \vec{R} e^{-Lt} f(\vec{a}, 0) - \nabla_a \cdot \int_0^t ds e^{-L(t-s)} \nabla_a \cdot [\vec{R}(s) f(\vec{a}, s)] \right]$$

avg over noise

$$\frac{\partial \langle f \rangle}{\partial t} + L \langle f \rangle = \nabla_a \cdot \int_0^t ds e^{-L(t-s)} \langle \vec{R}(t) \cdot \vec{R}(s) \rangle \nabla_a \langle f(\vec{a}, s) \rangle$$

$$\Rightarrow \left[\frac{\partial \langle f(\vec{a}, t) \rangle}{\partial t} + \nabla_a \cdot \langle \dot{a} \langle f \rangle \rangle = \nabla_a \cdot \underline{\underline{B}} \cdot \nabla_a \langle f(\vec{a}, t) \rangle \right]$$

Fokker-Planck

Langevin eq

$$\frac{dx}{dt} = p/m \quad \frac{dp}{dt} = -\frac{du}{dx} - \xi \frac{p}{m} + F_p(t)$$

$$\langle f_p(t) f_p(t') \rangle = 2 \xi k_B T \delta(t-t')$$

$$\vec{a} = \begin{pmatrix} x \\ p \end{pmatrix} \quad \vec{v} = \begin{pmatrix} p/m \\ -\frac{du}{dx} - \xi p/m \end{pmatrix}$$

$$\vec{F}(t) = \begin{pmatrix} 0 \\ \vec{f}_p(t) \end{pmatrix} \quad B = \begin{pmatrix} 0 & 0 \\ 0 & \xi k_B T \end{pmatrix}$$

Then $\frac{df(\vec{a}, t)}{dt} = -\frac{\partial}{\partial x} \left[\frac{p}{m} f(\vec{a}, t) \right] - \frac{\partial}{\partial p} \left[-u' - \xi \frac{p}{m} \right] f + \xi k_B T \frac{\partial^2}{\partial p^2} f(\vec{a}, t)$

only 1 matrix element

no noise or friction, standard Liouville eq

$$\text{eq, } \partial f / \partial t = 0$$

solution is $f(\vec{a}, t) \propto e^{-\beta H(\vec{a}, p) \ll p^2/2m + u}$

shows Langevin eq give Boltz statistics

check!

Consider $m \frac{d^2x}{dt^2} = -u'(x) - \xi \frac{dx}{dt} + F(t)$

one limit of Brownian behavior, $\frac{d^2x}{dt^2} \approx 0$

$$\frac{dx}{dt} = -\frac{1}{\xi} u'(x) + \frac{1}{\xi} F(t)$$

only one coordinate

$$\begin{aligned} \left\langle \frac{F(t)}{\xi} \cdot \frac{F(t')}{\xi} \right\rangle \\ = \underbrace{2 \frac{k_B T}{\xi}}_{\text{call "B"}} \delta(t-t') \end{aligned}$$

$$\frac{\partial f(x,t)}{\partial t} = -\frac{\partial}{\partial x} \left(-\frac{1}{\xi} u'(x) f(x,t) \right) + \frac{k_B T}{\xi} \frac{\partial^2}{\partial x^2} f$$

Smoluchowski

$$\frac{\partial f}{\partial t} = D \frac{\partial}{\partial x} e^{-\beta u} \frac{\partial}{\partial x} e^{\beta u} f(x,t) \quad D = k_B T / \xi$$

$$\text{b/c} = D \frac{\partial}{\partial x} e^{-\beta u} \left[\beta u' e^{\beta u} f + e^{\beta u} \frac{\partial f}{\partial x} \right]$$

$$= D \frac{\partial}{\partial x} \left[\beta u' f + \frac{\partial f}{\partial x} \right]$$

$$= \frac{\partial}{\partial x} \frac{u'}{\xi} f + \frac{k_B T}{\xi} \frac{\partial^2 f}{\partial x^2}$$

obviously stationary for $f(x,t) \propto e^{-\beta u(x)}$