

# Enhanced Sampling, Pt 2

Combining info from multiple simulations

Last time  $Z_X @ T_1, \dots, T_N$   
or umbrellas  $@ Q_1, \dots, Q_N$

Showed how for US, can stitch together  
"by hand" and for RX just use lowest temp

Idea, combine info from all sims

One method: Weighted Histogram Analysis  
Method (wham)

Annoying to derive (Tuckerman 8.8)

Idea:

Sim in modified Ensemble eg

$$P_i(X) = \frac{e^{-\beta u(x) + \frac{1}{2} k(Q-Q_i)^2}}{Z_i}$$

$$Z_i = \int dX e^{-\beta u(x) + \frac{1}{2} k(Q-Q_i)^2}$$

$Q(x) =$  some function of  $q$ 's

$$P_i(Q) = \int \delta(Q(x) - Q_i) e^{-\beta(\mu(x) + \frac{1}{2}k(Q - Q_i)^2)} / Z_i$$

But want  $P(Q)$  ie w/o bias

Suppose have cfg

$$x_1^i \dots x_n^i, \quad P(x_n^i) = e^{-\beta\mu(x_n^i)} \cdot e^{-\beta \frac{1}{2}k(Q - Q_i)^2} / Z_i$$

$$\text{and } P(x_n) = e^{-\beta\mu(x_n)} / Z$$

$$\Rightarrow P(x_n) = \sum_i Z_i P(x_n^i) e^{+\beta \frac{k}{2}(Q - Q_i)^2}$$

$$\text{So } \langle A \rangle = \frac{1}{Z} \sum_{i=1}^I Z_i e^{\beta \frac{k}{2}(Q - Q_i)^2} A(x_n^i)$$

reweighting

idea is to estimate  $Z_i$ 's by comparing data from  $i$  &  $j$  & minimizing a variance in data

Result w/ same assumptions:

$$A_k = -k_B T \log Z_k$$

$$P(Q) = \frac{\sum_{i=1}^N n_i P_i(Q)}{\sum_{i=1}^N n_i e^{-\beta \frac{1}{2}k(Q - Q_i)^2} e^{\beta(A_k - A_0)}} \quad \swarrow Z_0 / Z_k$$

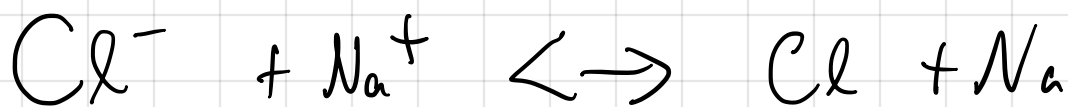
$$\text{where } \exp(-\beta(A_k - A_0)) \equiv \int dQ \underline{P(Q)} e^{-\beta \frac{1}{2}k(Q - Q_0)^2}$$

This method can let us compute

$$A(Q) = -k_B T \log P(Q)$$

and hence  $A(Q_B) - A(Q_A)$ , free energy difference between 2 states if differ in coordinate

Sometimes states better described by a change in hamiltonian, eg



suppose state 1 has  $H_1 = KE + U_1(x)$

and  $H_2 = KE + U_2(x)$

Then  $H(\lambda) = KE + (1-\lambda)U_1(x) + \lambda U_2(x)$

can be simulated to try to get free energy between states

$$Q(\lambda) = C \int dX e^{-\beta H(X, \lambda)}$$

$$A = -k_B T \log Q(\lambda) = -k_B T \log Z(\lambda) + k_B \epsilon.$$

$$\frac{\partial A}{\partial \lambda} = -k_B T \frac{\partial Q}{Q \partial \lambda} = -k_B T \frac{\partial Z}{Z \partial \lambda}$$

$$\frac{\partial Z}{\partial \lambda} = \int dq^{3N} -\beta \frac{\partial u}{\partial \lambda} e^{-\beta u(q, \lambda)}$$

$$\text{so } \frac{\partial A}{\partial \lambda} = \left\langle \frac{\partial u}{\partial \lambda} \right\rangle_{\lambda} \quad \text{if linear}$$

$$\Delta A = \int_0^1 d\lambda \frac{\partial A}{\partial \lambda} = \int_0^1 d\lambda \left\langle \frac{\partial u}{\partial \lambda} \right\rangle_{\lambda} = \int_0^1 \langle u_2 - u_1 \rangle_{\lambda} d\lambda$$

Thermo Integration

In practice, do simulations at different  $\lambda_i$  in range, and then do whm to get  $A(\lambda)$  to compute  $A(1) - A(0)$

In contrast, direct/end point switching  
(Free Energy Perturbation)

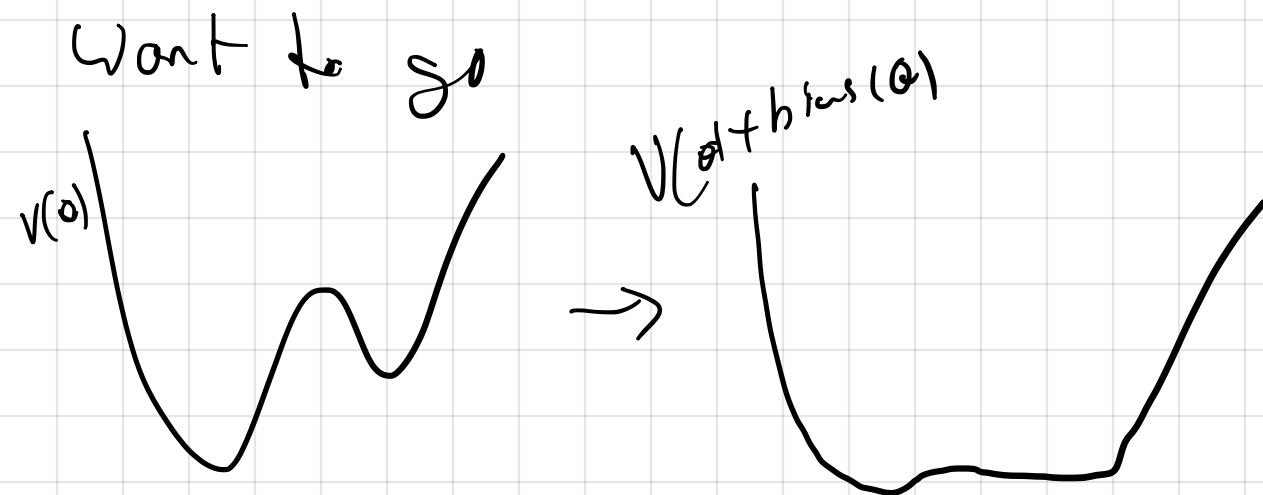
$$A_2 - A_1 = -k_B T \log Z_2 - k_B T \log Z_1$$

$$= -k_B T \log Z_2 / Z_1$$

$$= -k_B T \log \left( \left\langle e^{-\beta(u_2 - u_1)} \right\rangle_1 \right)$$

# Another Idea: Metadynamics

Want to go



"ideal" bias =  $-V(Q)$

Add gaussians every  $\Delta t$  steps

$$V(Q, t + \Delta t) = V(Q, t) + h e^{-\frac{(Q - Q(t))^2}{2\Delta^2}}$$

$h$  is height,  $\Delta$  is width  
center is current  $Q$  position

Well tempered,  $h(Q) = e^{-\gamma V(Q)}$

bias added is smaller where bias exists