

Van der Waal's Eqn & Intro to Simulation

Last time, perturbation theory, i.e. $U(r) = U_0(r) + U_1(r)$
 U_1 is small compared to U_0

Have to compute averages like

$$\langle e^{-\beta U_1} \rangle_0 \text{ where } \langle a \rangle_0 = \int dr a(r) \frac{e^{-\beta U_0(r)}}{Z_0}$$

$$A = -k_B T \log Q = -k_B T \log \left[\frac{Z_0}{N! \lambda^{3N}} \right] - k_B T \log \langle e^{-\beta U_1} \rangle_0$$
$$A_1 \approx \beta \langle U_1 \rangle_0 - \beta/2 \text{Var}_0(U_1)$$

But what is $\langle U_1 \rangle_0$ for small U_1 ?

$$\text{Remember } \langle U_0 \rangle_0 = 2\pi N \rho \int_0^\infty dr r^2 U_0(r) g_0(r)$$

where $g_0(r)$ is $g(r)$ when $U_1 = 0$

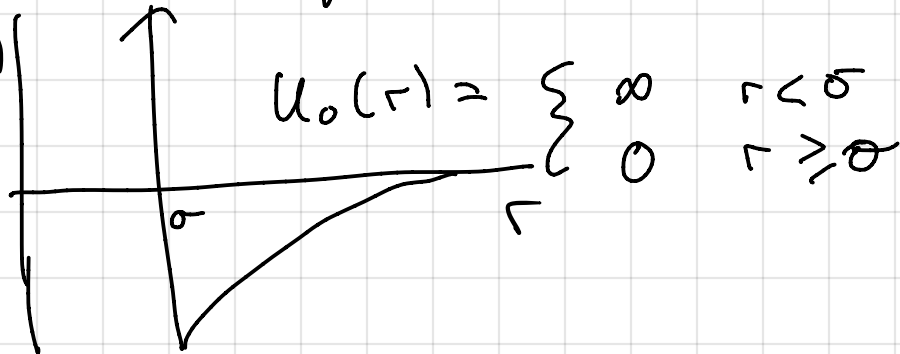
$$\text{same analysis gives } \langle U_1 \rangle_0 = 2\pi N \rho \int_0^\infty dr r^2 U_1(r) g_0(r)$$

Now know A_1 to low order

Point of perturbation theory is to start
with a reference system we can "solve"

Simple potential is hard sphere +

attraction $u(r)$
 $= u_0 + u_1$



in low density limit, for unperturbed $g_0(r) \approx e^{-\beta u_0(r)} = \begin{cases} 0 & r < \sigma \\ 1 & r \geq \sigma \end{cases}$



$$\equiv \Theta(r - \sigma)$$

$$A^{(1)} \approx 2\pi N\rho \int_0^\infty r^2 u_1(r) g_0(r) dr = 2\pi N\rho \int_\sigma^\infty r^2 u_1(r) dr < 0$$

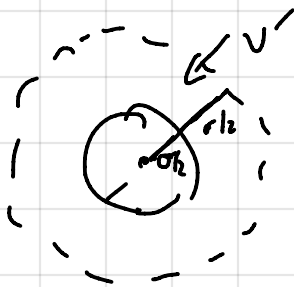
$$a \equiv -2\pi \int_\sigma^\infty r^2 u_1(r) dr > 0 = -a N\rho = -a N^2/V$$

To get A^0 , need $Z^{(0)}$. for ideal gas $Z = V^N$

for low density gas, with repulsion $Z_0 = V_{\text{avail}}^N$

$$V_{\text{available}} = V - V_{\text{excluded}}$$

What is V_{excluded} for a hard sphere particle



no particle can be closer than

$$R = \sigma, \text{ so } V' = \frac{4}{3}\pi\sigma^3$$

Not obvious, But this double counts exclusion b/c particle i excludes j & vice versa, so

$$V_{\text{excluded}} = N \cdot \frac{1}{2} \cdot \frac{4}{3}\pi\sigma^3 = Nb \quad \leftarrow \frac{2}{3}\pi\sigma^3$$

$$\Rightarrow Z_0 = (V - Nb)^N$$

$$A \approx -k_B T \log \left[\frac{(V - Nb)^N}{N! \Lambda^{3N}} \right] - a N^2 / V$$

$$P = -\left(\frac{\partial A}{\partial V}\right) = +k_B T N \cdot \frac{1}{V - Nb} - \frac{a N^2}{V^2}$$

$$= \frac{N k_B T}{V - Nb} - \frac{a N^2}{V^2}$$

$$\text{or } \beta P = \frac{\rho}{1 - \rho b} - a \rho^2 \beta \quad \star \quad \text{Van der waal's eqn of state}$$

$$\frac{1}{1-x} = -\frac{d}{dx} \log(1-x) = 1 + x + x^2 + \dots$$

$$\beta P \approx \rho(1 + \rho b + \rho^2 b^2 + \dots) - a \rho^2 \beta$$

$$\approx \rho + \rho^2 \frac{(b - a\beta)}{\beta_2} + \rho^3 \frac{b^2}{\beta_3} + \dots$$

within VDW approx

Note, Van der Waals eqn of state has a change in behavior corresponding to a critical point. Can predict some "critical behavior" (see pg 175-177) but we will discuss more w/ phase transitions

These were actually some of the first things people tried to compute with simulations, either to solve problems impossible by hand or to give as inputs to theories [e.g. equations depending on $g(r)$]

E.g. do system of disks crystallize?
first shown on a computer by Alder & Wainwright 1957. Crystal actually has more entropy!

How do we do these simulations?

We want to compute quantities like

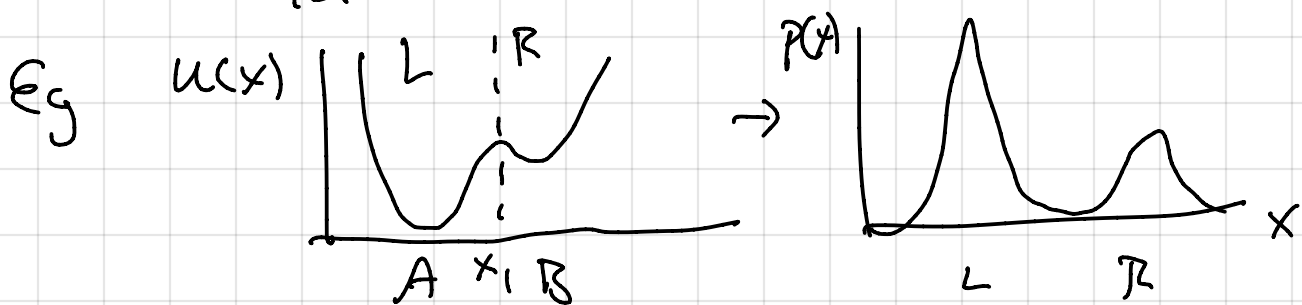
$$\langle A \rangle = \int d\vec{x} A(\vec{x}) P(\vec{x}) \quad \text{where}$$

$P(\vec{x})$ might be something like $e^{-\beta \chi(\vec{x})} / \int d\vec{x} e^{-\beta \chi(\vec{x})}$

If we know the prob. func., then we

can do this integral by "quadrature" (discretization)

$$\langle A \rangle \approx \sum_{i=1}^N A(\vec{x}_i) P(\vec{x}_i) \Delta x$$



Prob of being on left is $A(x) = \begin{cases} 1 & x < x_1 \\ 0 & x > x_1 \end{cases}$
 χ_A , indicator function

however, this does not work in higher dimensions

b/c num points is $(L/\Delta x)^d \sim e^{d \log(L/\Delta x)}$

Idea of both MC & MD: rather than generate x_i on a grid w/ prob 1, generate $x_i \propto P(x)$ somehow

$$\text{Then } \langle A \rangle \approx \frac{1}{N} \sum_{i=1}^N A(x_i)$$

One way to do this is to generate a "Markov Chain", rule $x_i \rightarrow x_{i+1}$ that only depends on x_i (not $x_1 \dots x_{i-1}$)

If we also satisfy detailed balance

$$P(x_i) P(x_i \rightarrow x_{i+1}) = P(x_{i+1}) P(x_{i+1} \rightarrow x_i)$$

$P(x_i \rightarrow x_{i+1})$ has 2 parts

$$= P_{\text{gen}}(x_i \rightarrow x_{i+1}) P_{\text{acc}}(x_i \rightarrow x_{i+1})$$

$$P_{\text{acc}}(x_i \rightarrow x_{i+1}) = \frac{P(x_{i+1}) P_{\text{gen}}(x_{i+1} \rightarrow x_i)}{P(x_i) P_{\text{gen}}(x_i \rightarrow x_{i+1})} P_{\text{acc}}(x_{i+1} \rightarrow x_i)$$

How can we do this? One way, $r(x_i \rightarrow x_{i+1})$

Metropolis rule $P_{\text{acc}}(x_i \rightarrow x_{i+1}) = \min(1, r(x_i \rightarrow x_{i+1}))$

Algorithm Start @ x_i

→ propose x_{i+1} with prop $P_{\text{gen}}(x_i \rightarrow x_{i+1})$
gen $r \in (0, 1)$
if $r < P_{\text{acc}}(x \rightarrow x_{i+1})$, move to x_{i+1}
if not, keep x_i (for statistics)
as x_{i+1}

Tune P_{acc} to get accept prob. Often $(0, 1)$
move is uniform $x_{i+1} = x_i + \xi \cdot \sqrt{\frac{1}{2}}$

For canonical, if uniform gen
 $r(x_i \rightarrow x_{i+1}) = P(x_{i+1})/P(x_i) = e^{-\beta(E(x_{i+1}) - E(x_i))}$

Another more advanced example:

Turns out, const pressure

$$\Omega(N, P, T) = \frac{1}{V_0} \int_0^\infty dV e^{-\beta PV} Q(N, V, T)$$

$$\left(\text{like how } Q = \frac{1}{\xi_0} \int_0^\infty dE e^{-\beta E} \Omega(N, V, E) \right)$$

What if we want to do MC & keep const pressure, have to adjust the volume

$$\Delta(N, P, T) \propto \int_0^{\infty} dV e^{-\beta PV} \int d\vec{q}^{3N} e^{-\beta U(\vec{q})}$$

$$= \int_0^{\infty} dV e^{-\beta PV} \cdot V^N \int d\vec{s}^{3N} e^{-\beta U(\vec{s} V^{1/3})}$$

$$= \int_0^{\infty} dV \int d\vec{s}^{3N} e^{-\beta(PV + U(\vec{s} V^{1/3}) - \frac{N}{3} \log V)}$$

note:
 $V^N = e^{N \log V}$

so now $P("x") = \exp[-\beta(PV + U - \frac{N}{3} \log V)] / \Delta(N, P, T)$

So can make Volume moves,
 $V_{i+1} = V_i + \xi$, $\xi \in (-\delta, \delta)$

$$A(V_i \rightarrow V_{i+1}) = \min[1, \exp[-\beta P(V_{i+1} - V_i) + N \log(V_{i+1}/V_i) - \beta(\epsilon_{i+1} - \epsilon_i)]]$$

$$\epsilon_{i+1} = U(\vec{s}, V_{i+1}^{1/3}), \quad \epsilon_i = U(\vec{s}, V_i^{1/3})$$

This is probably an expensive calculation unless
 $U(\lambda \vec{q}) = \lambda^n U(\vec{q})$

Conclusion: Monte Carlo is a very powerful (Easy) and general method for sampling from a distribution, not just in chemistry. Useful in statistics, data science, machine learning...

Downsides: (1) only one thing happens at a time
 sometimes many moves rejected (inefficient)
 (2) Generally good for static properties,
 not likely any connection to real time, so
 not good if you want info about kinetics